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Davies Coupling
in a **Shallow-Water** Model

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Motivation

High resolution NWP techniques:

- ★ **global model with variable resolution**

ARPEGE 22 – 270 km

- ★ **low resolution driving model
with nested high resolution LAM**

DWD/GME → DWD/LM 60 km → 7 km

- ★ **combination of both methods**

ARPEGE → ALADIN/LACE → ALADIN/SLOK

25 km → 12 km → 7 km

WHY **NESTED MODELS** IMPROVE WEATHER - FORECAST

- ❖ the surface is more accurately characterized (orography, roughness, type of soil, vegetation, albedo ...)
- ❖ more realistic parametrizations might be used, eventually some of the physical processes can be fully resolved in LAM
- ❖ own assimilation system \Rightarrow better initial conditions (early phases of integration)

Shallow-water equations

- 1D system (Coriolis acceleration not considered)
- linearization around resting background

$(g, H = \text{const})$

$$\frac{\partial u}{\partial t} = -g \frac{\partial h}{\partial x},$$

$$\frac{\partial h}{\partial t} = -H \frac{\partial u}{\partial x}$$

- forward-backward scheme
- centered finite differences

} DISCRETIZATION

Davies relaxation scheme

continuous formulation in **shallow-water system**

$$\frac{\partial u}{\partial t} = -g \frac{\partial h}{\partial x} - K(x)(u - u_{DM}),$$

$$\frac{\partial h}{\partial t} = -H \frac{\partial u}{\partial x} - K(x)(h - h_{DM}),$$

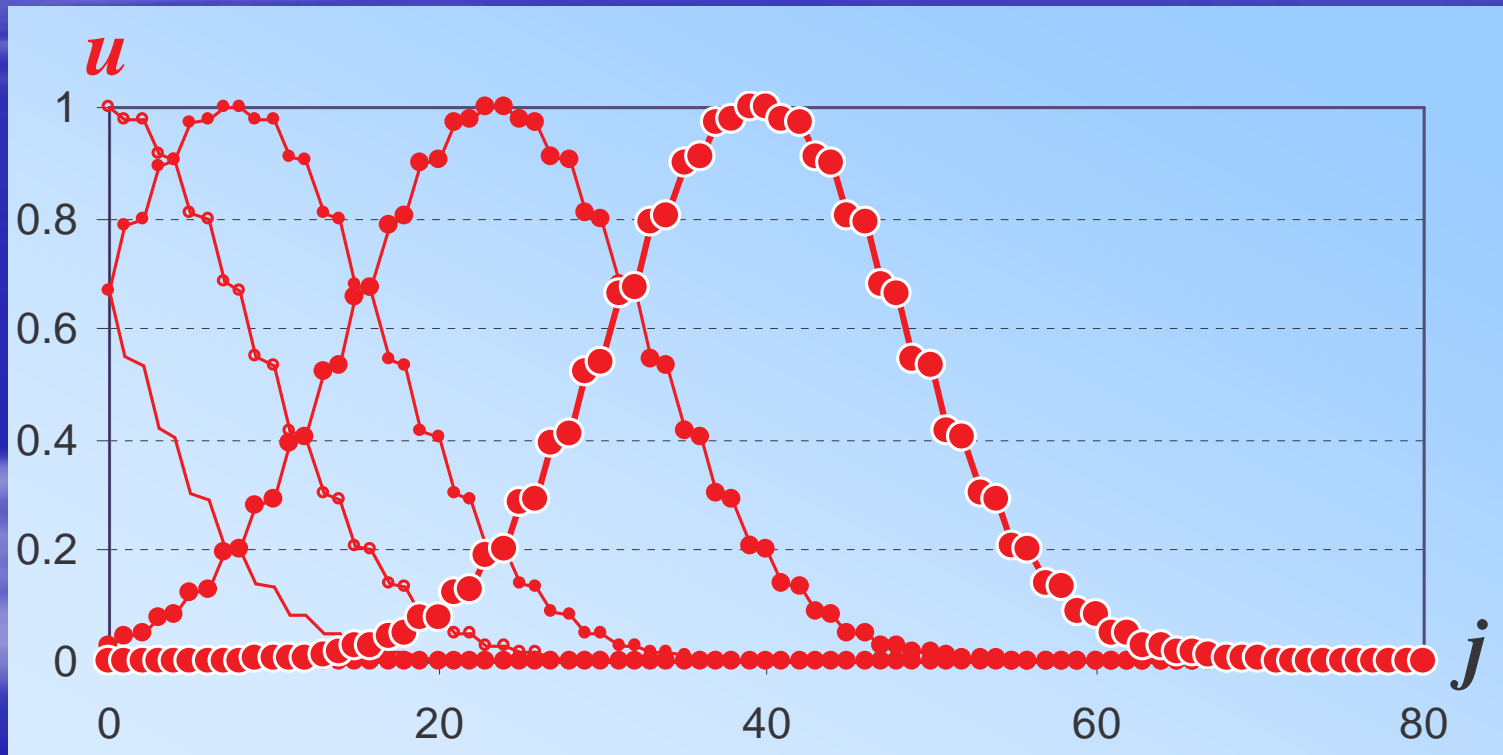
$$K(x) > 0$$

discrete formulation - general formalism:

$$X^+ = (1 - \beta) \cdot X_{LAM}^+ + \beta \cdot X_{DM}^+ \quad X = \begin{pmatrix} u \\ h \end{pmatrix}$$

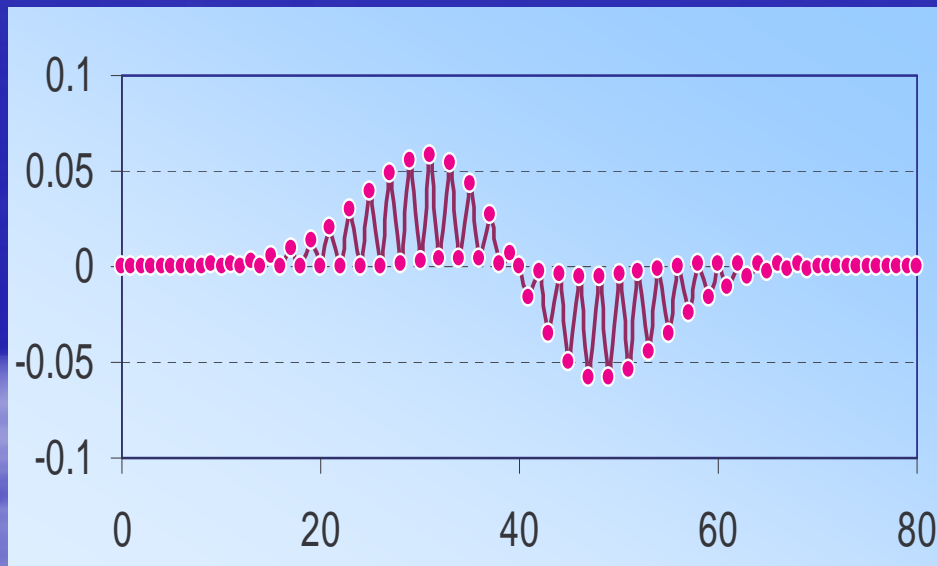
PROPERTIES OF DAVIES RELAXATION SCHEME

Input of the wave from the driving model

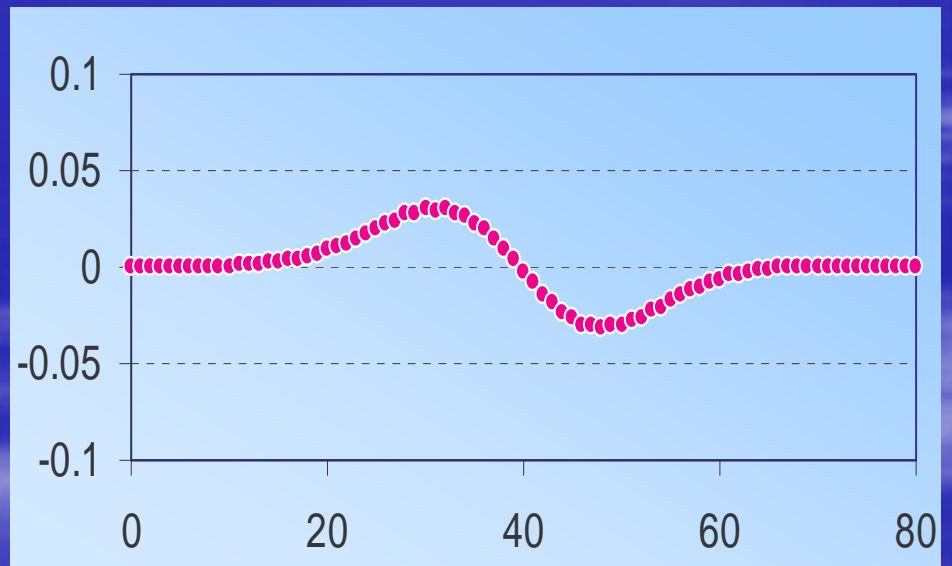


Difference between numerical and analytical solution

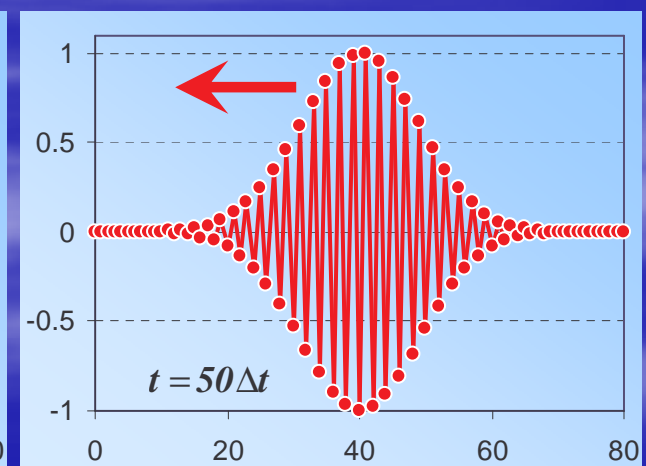
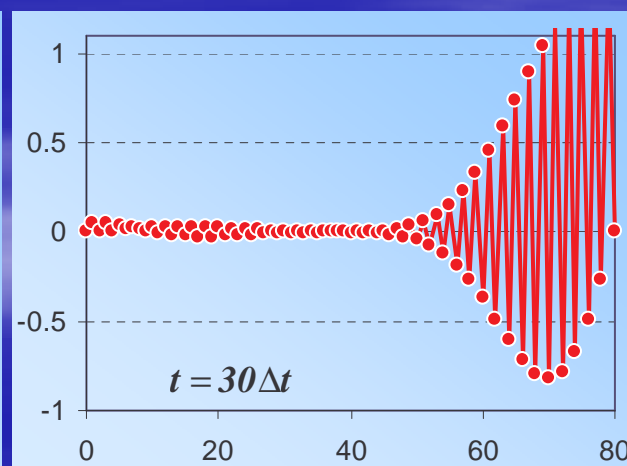
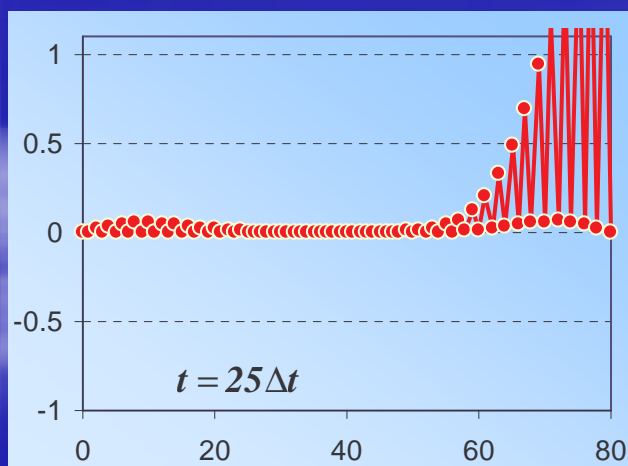
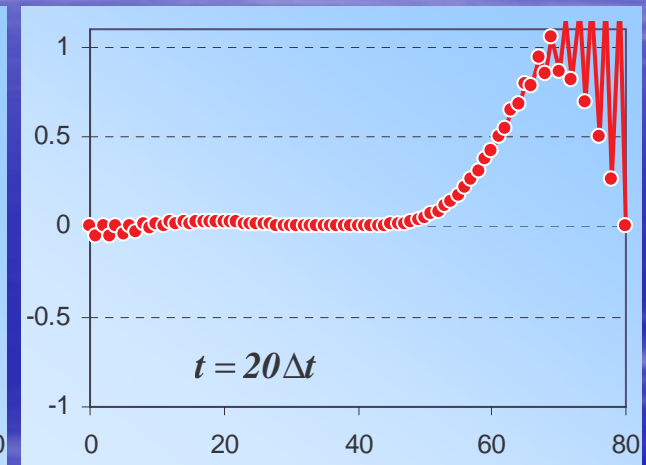
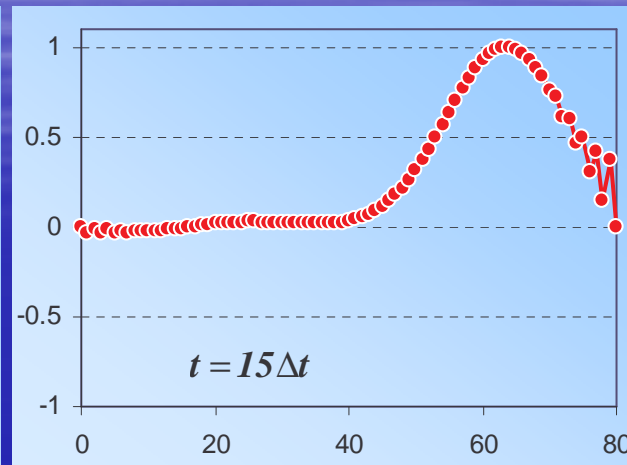
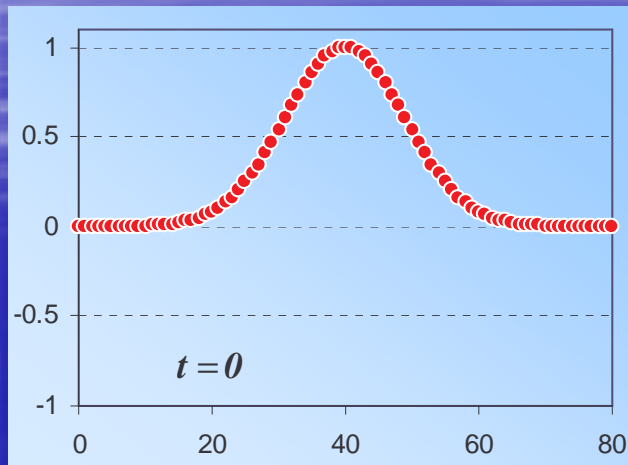
(no relaxation)



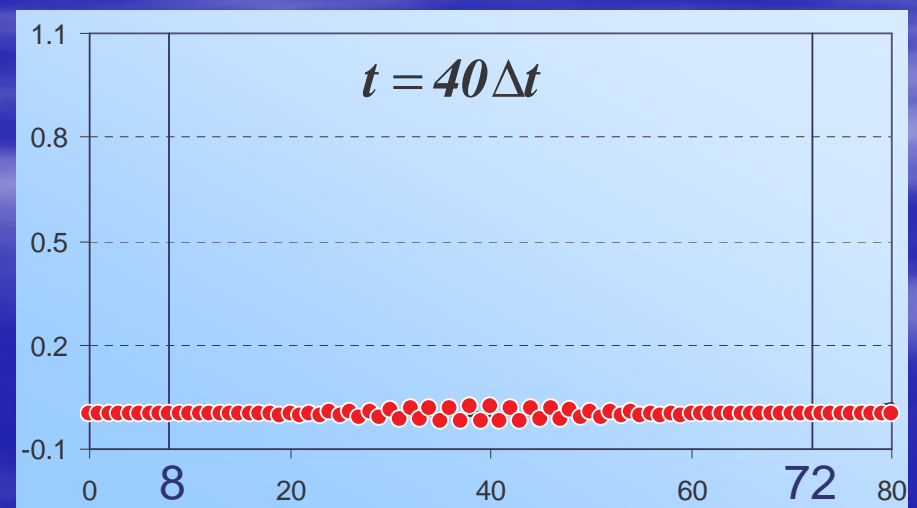
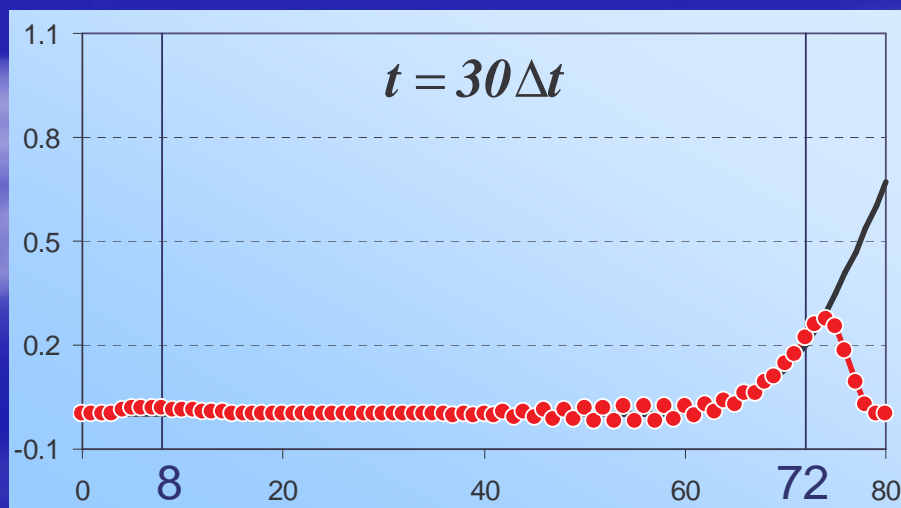
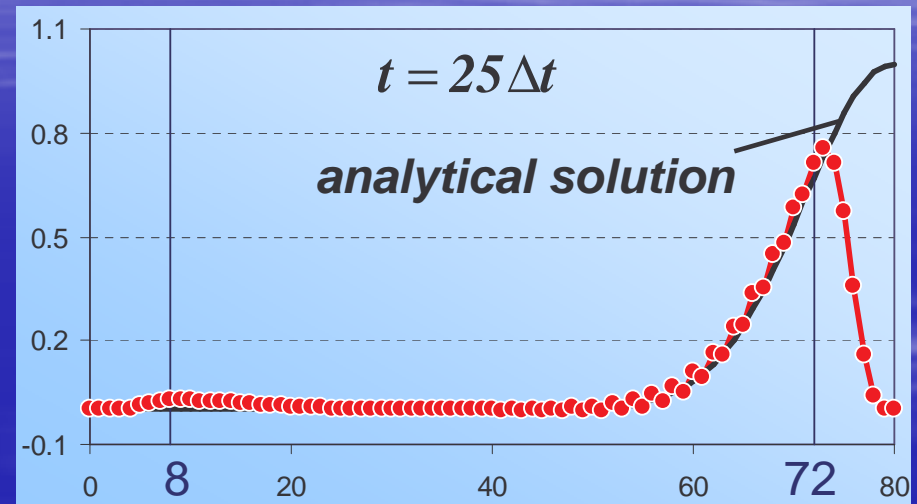
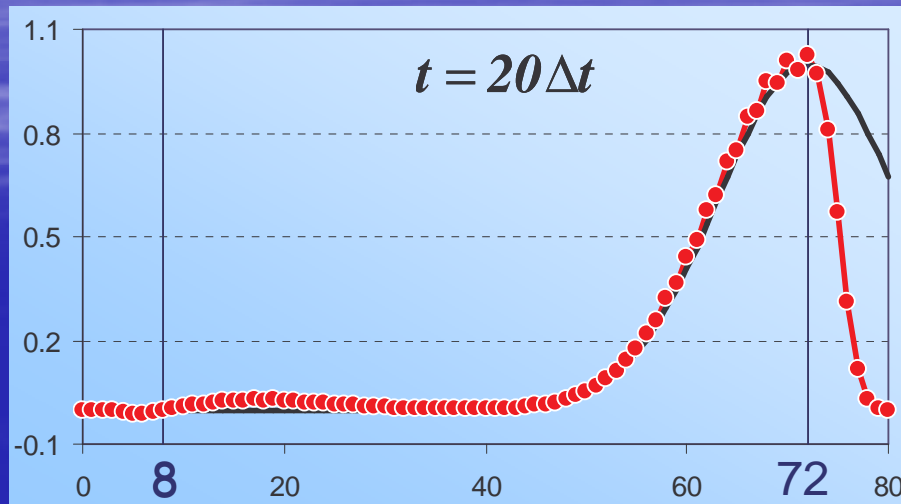
8-point relaxation zone



Outcome of the wave, which is not represented in driving model



8-point relaxation zone

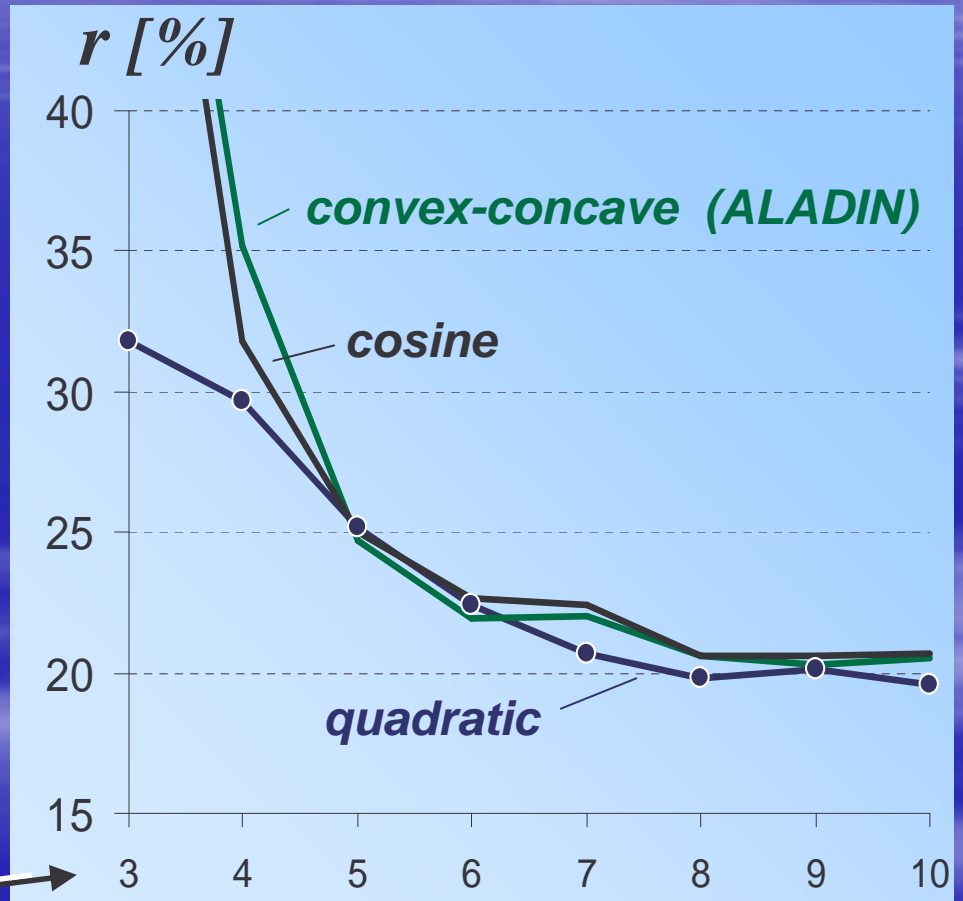
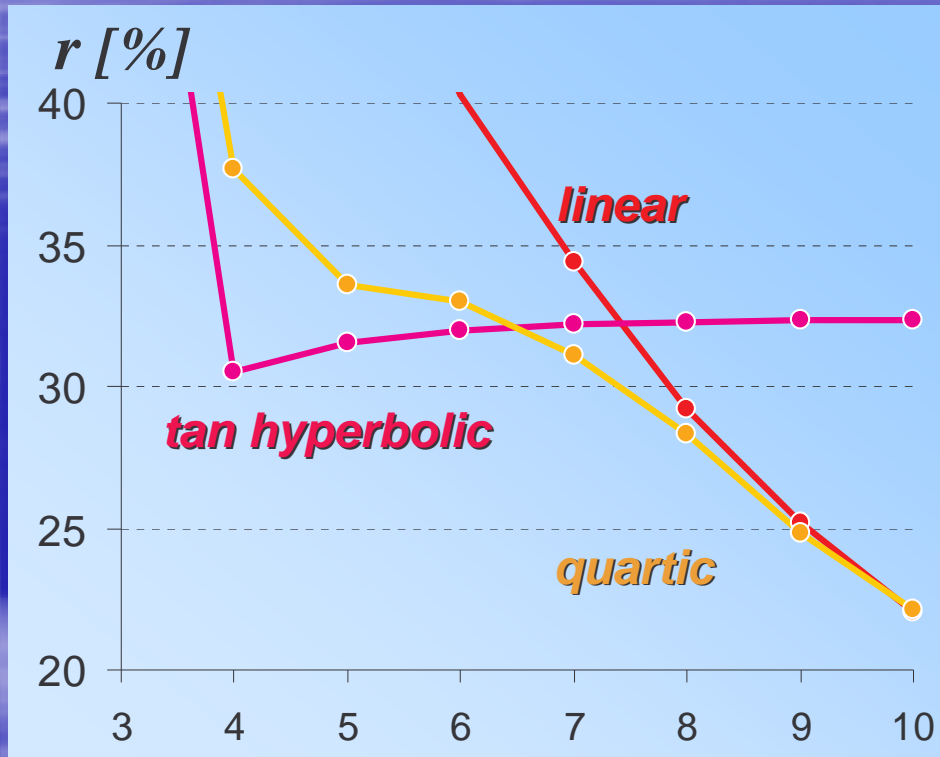


Minimalization of the reflection

- *weight function*
- *width of the relaxation zone*
- the velocity of the wave (4 different velocities satisfying CFL stability criterion)
(simulation of dispersive system)
- wave-length $\{10\Delta x, 20\Delta x, 40\Delta x\}$

Choosing the weight function

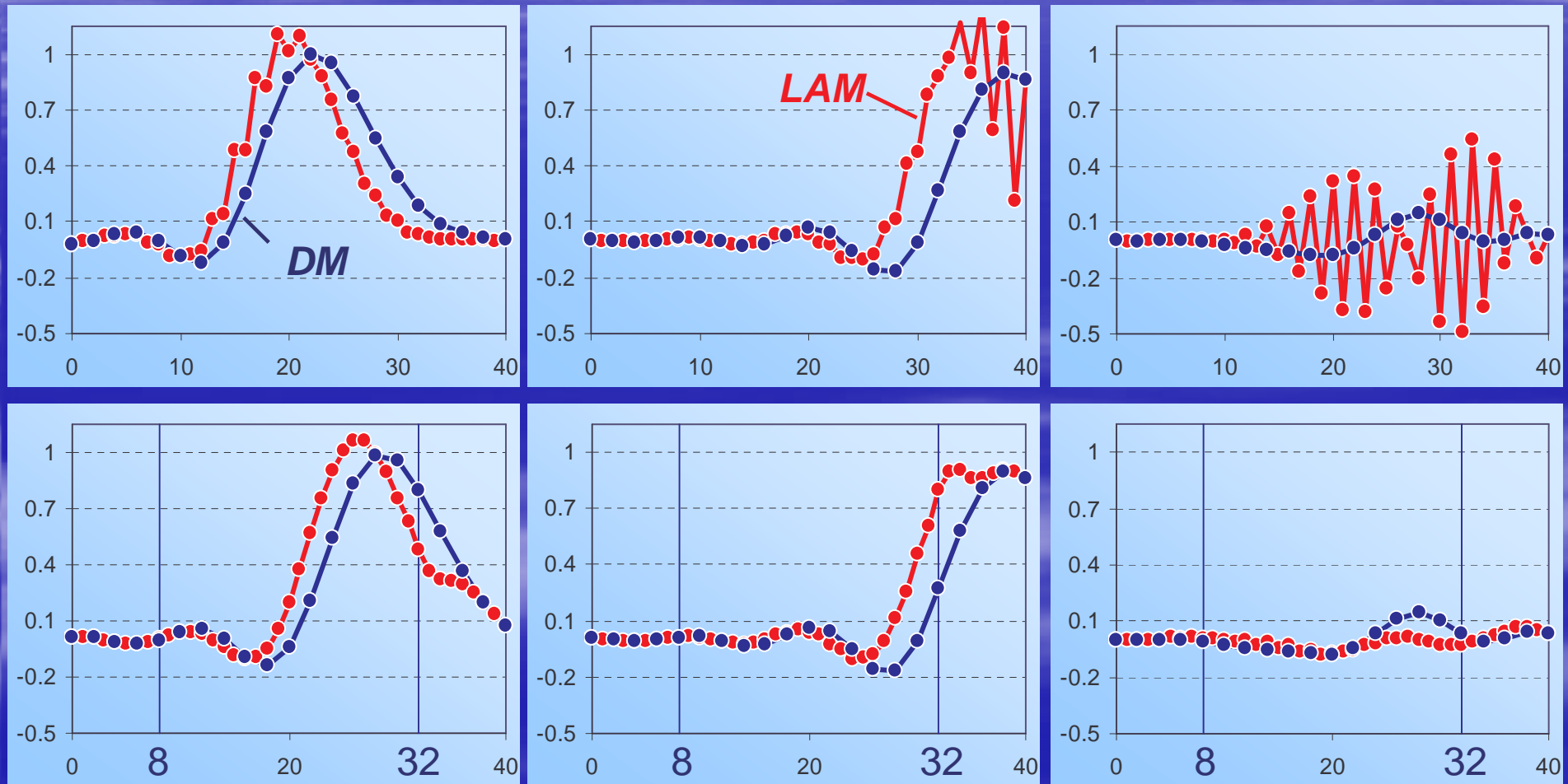
testing criterion - critical reflection coefficient r



number of points in relaxation zone

$$H_{LAM} = 0.81 H_{DM} \quad (c_{LAM} = 0.9 c_{DM})$$

(more accurate representation of surface)



DM-driving model

LAM-limited area model